# Artificial Intelligence csc 665

## Machine Learning III

4.18.2024

- Search: make decisions by looking ahead
- Logic: deduce new facts from existing facts
- Constraints: find a way to satisfy a given specification
- Probability: reason quantitatively about uncertainty
- Learning: make future predictions from past observations

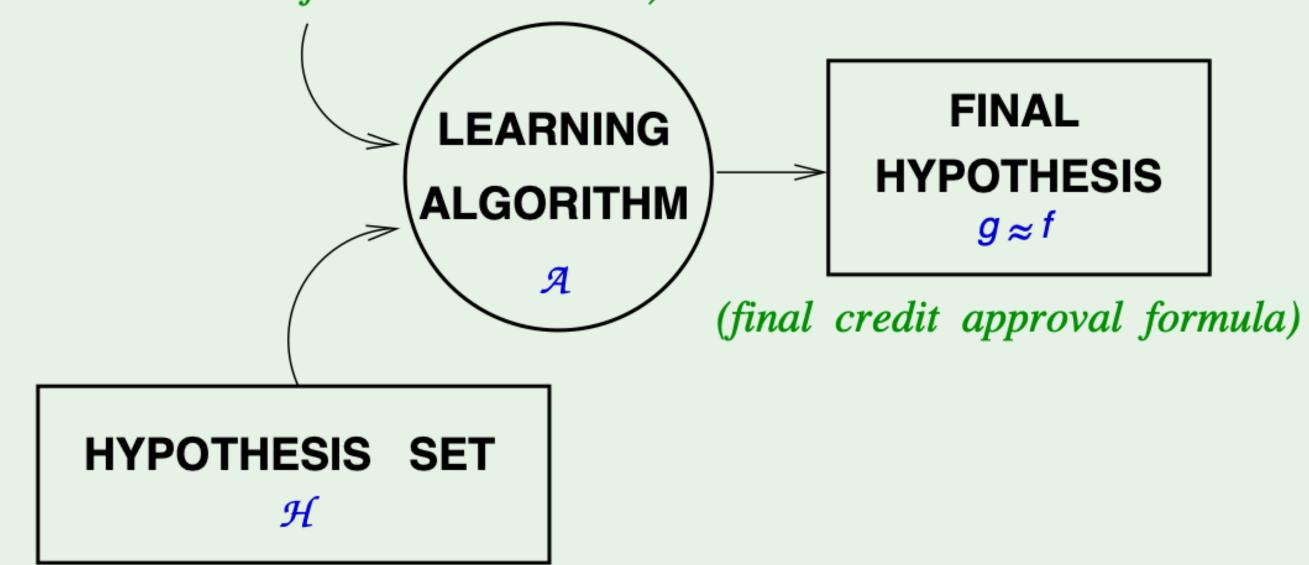
#### **UNKNOWN TARGET FUNCTION**

(ideal credit approval function)

#### TRAINING EXAMPLES

$$(\mathbf{x}_{1}, y_{1}), \dots, (\mathbf{x}_{N}, y_{N})$$

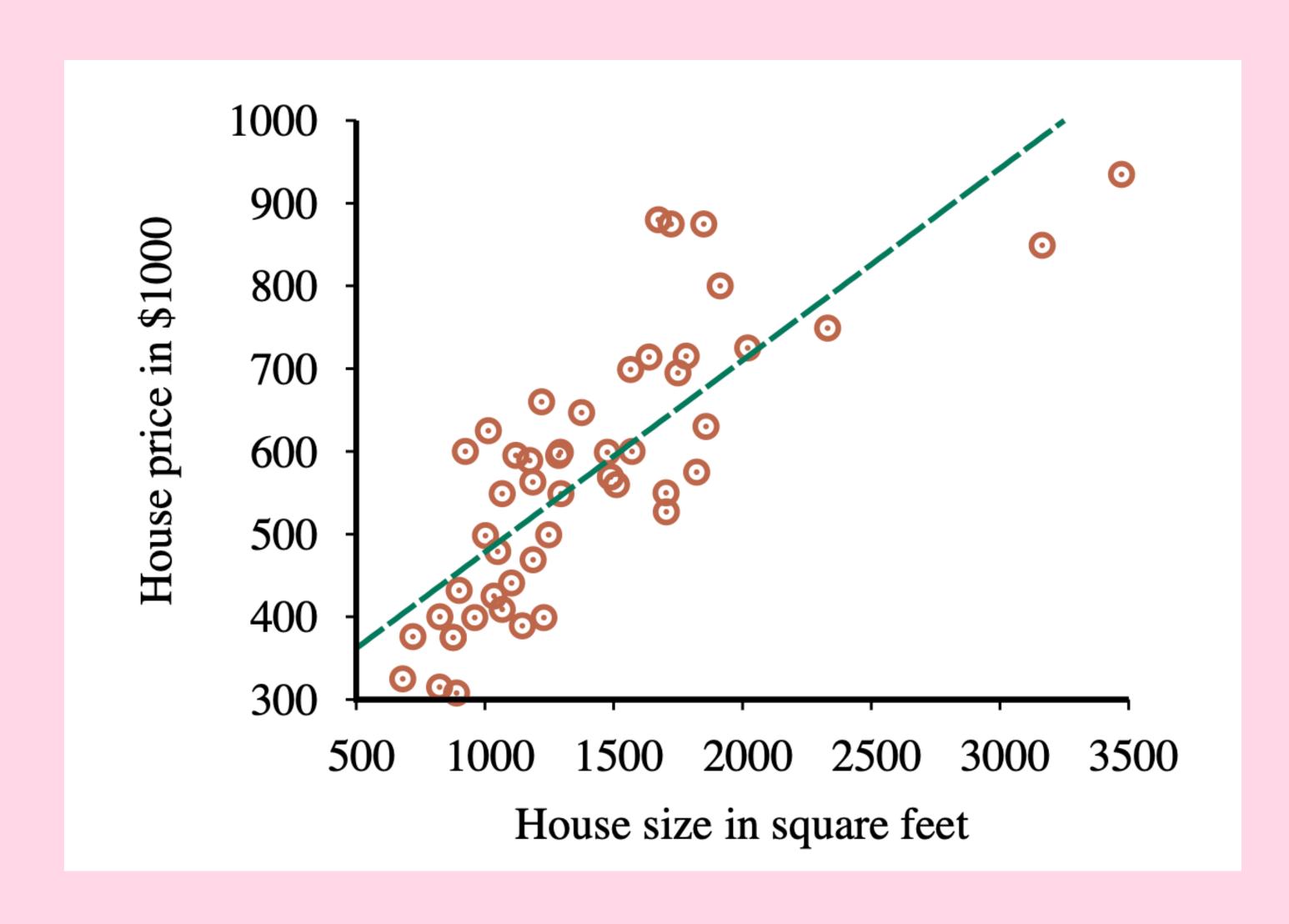
(historical records of credit customers)



(set of candidate formulas)

# Modeling

#### Example: predicting housing prices

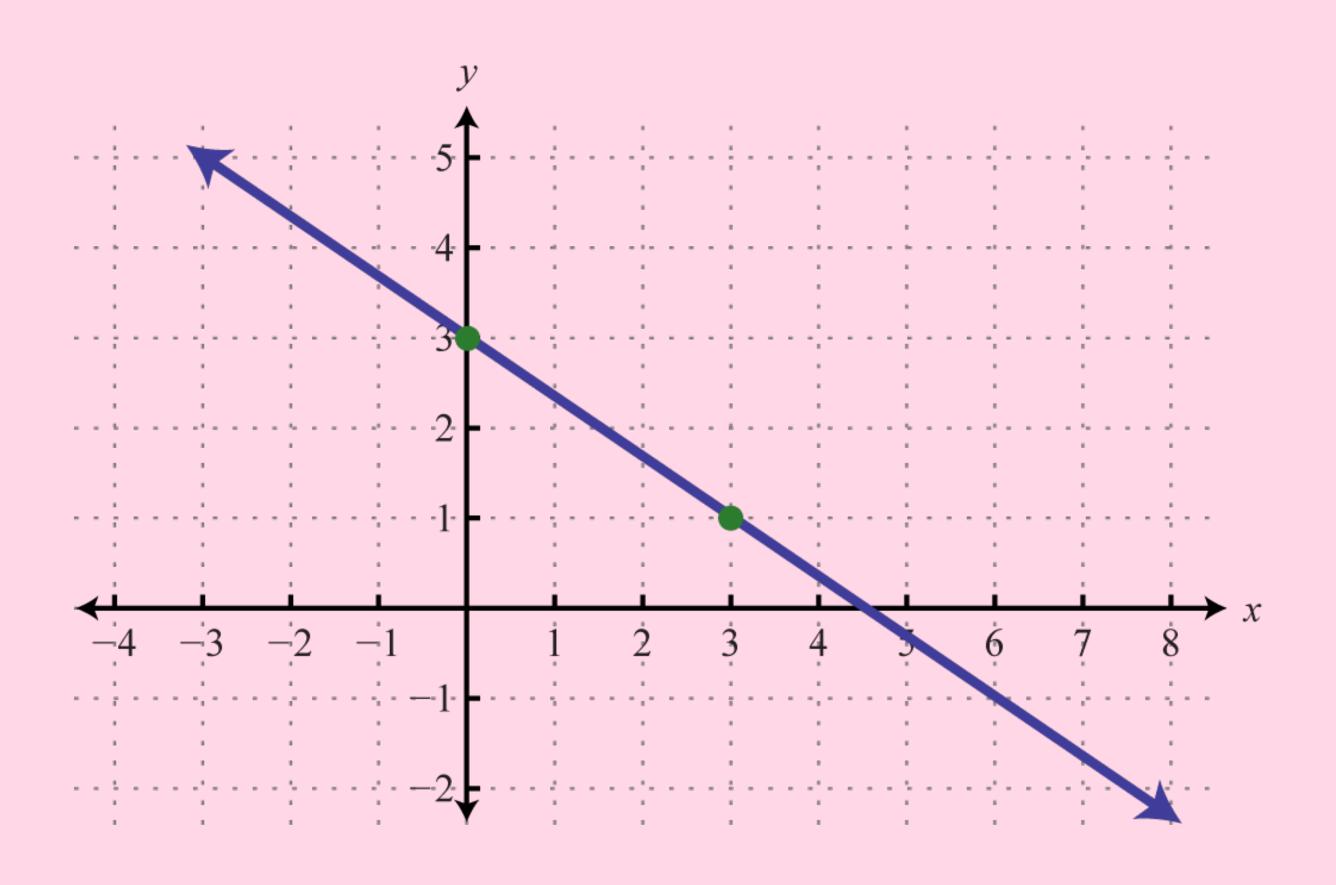


#### Linear models

- Hypothesis class: the set of all linear functions  $h(x) = w_1 x + w_0$
- Cost: squared error

$$C(h) = \sum_{i=1}^{\infty} (y_i - h(x_i))^2$$

• Optimizer: analytical solutions for  $w_0$ ,  $w_1$  via calculus



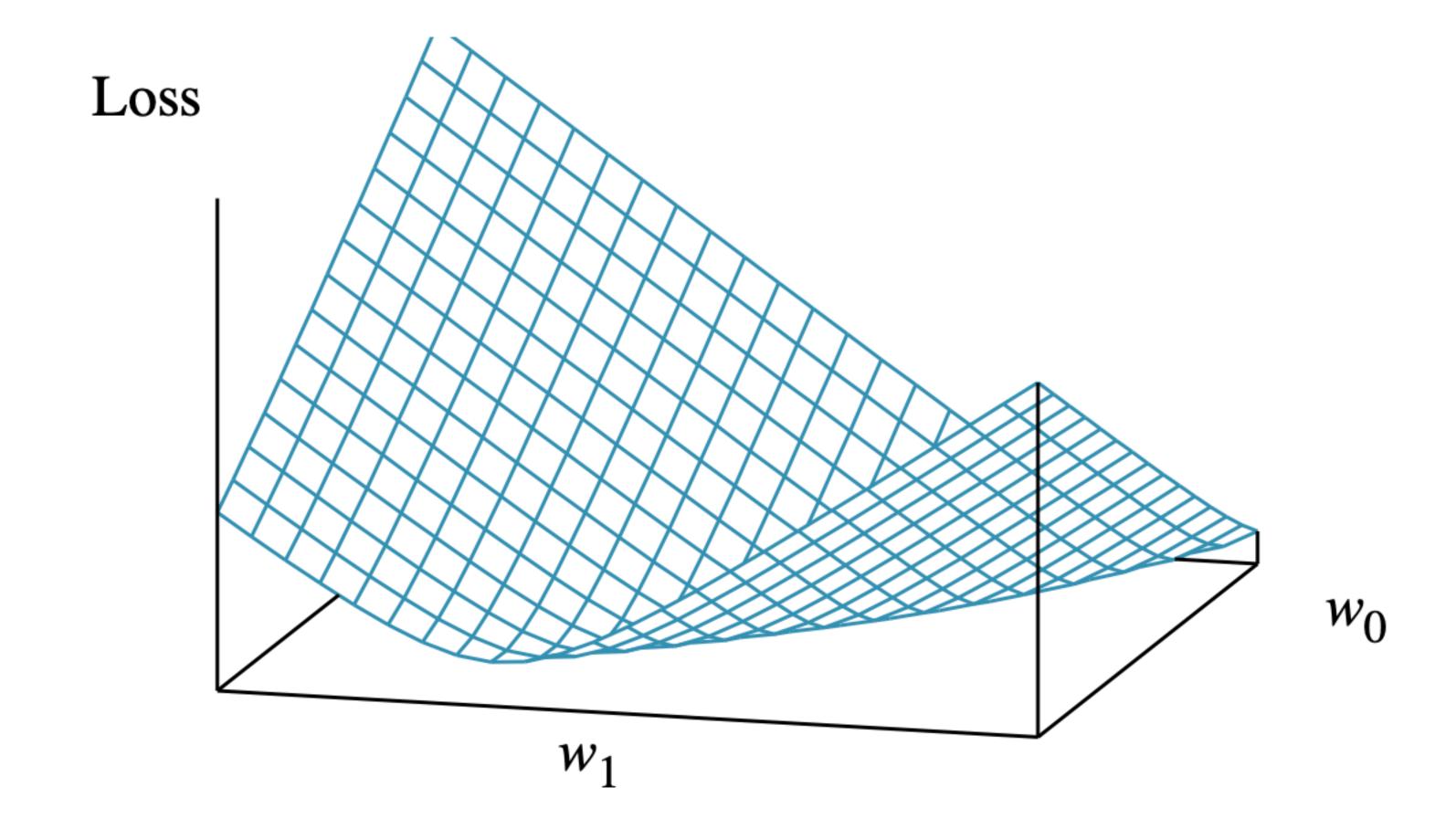
#### Optimizer: calculus

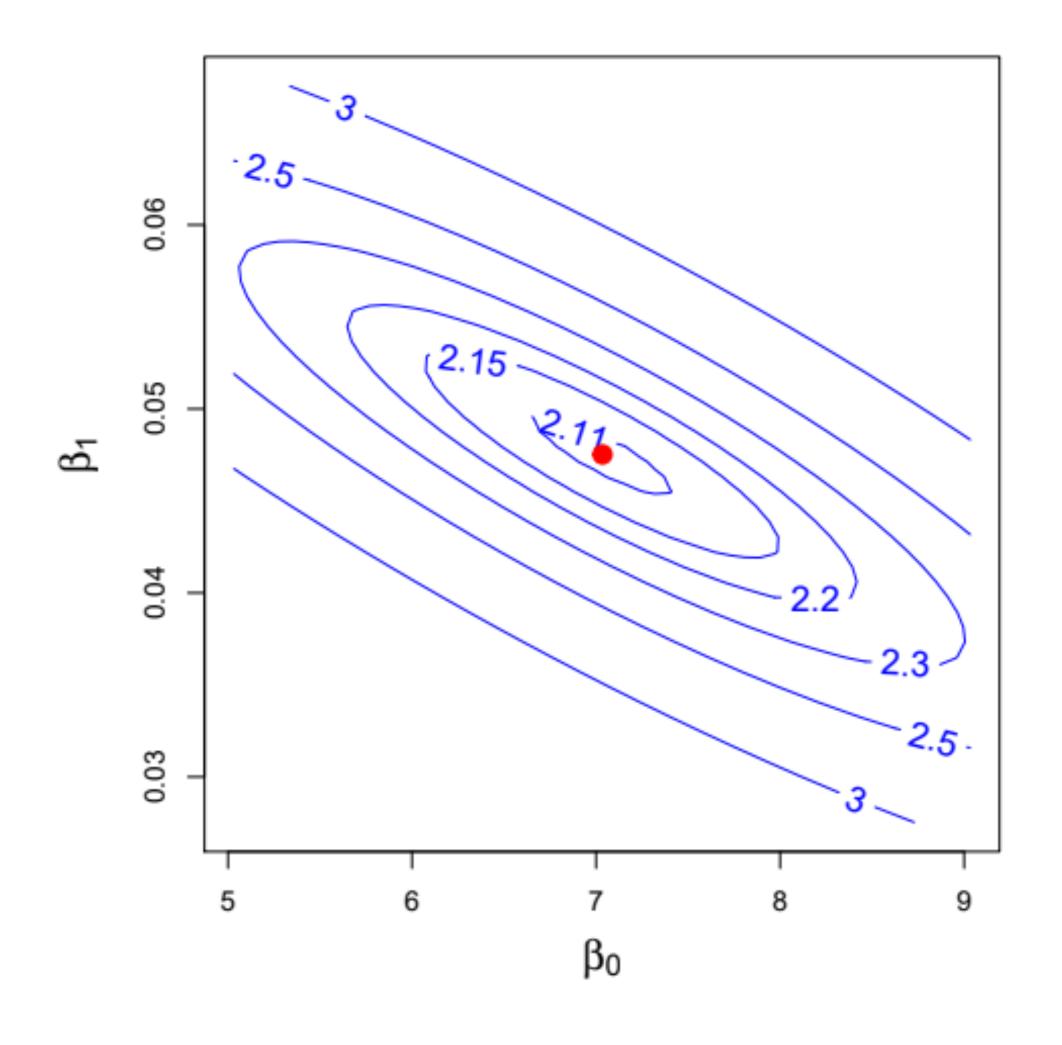
- How do we find the values of  $w_0$  and  $w_1$  that minimize  $C(w_0, w_1)$ ?
- Because  ${\mathcal H}$  is simple, we can optimize directly with calculus!
- Solutions:

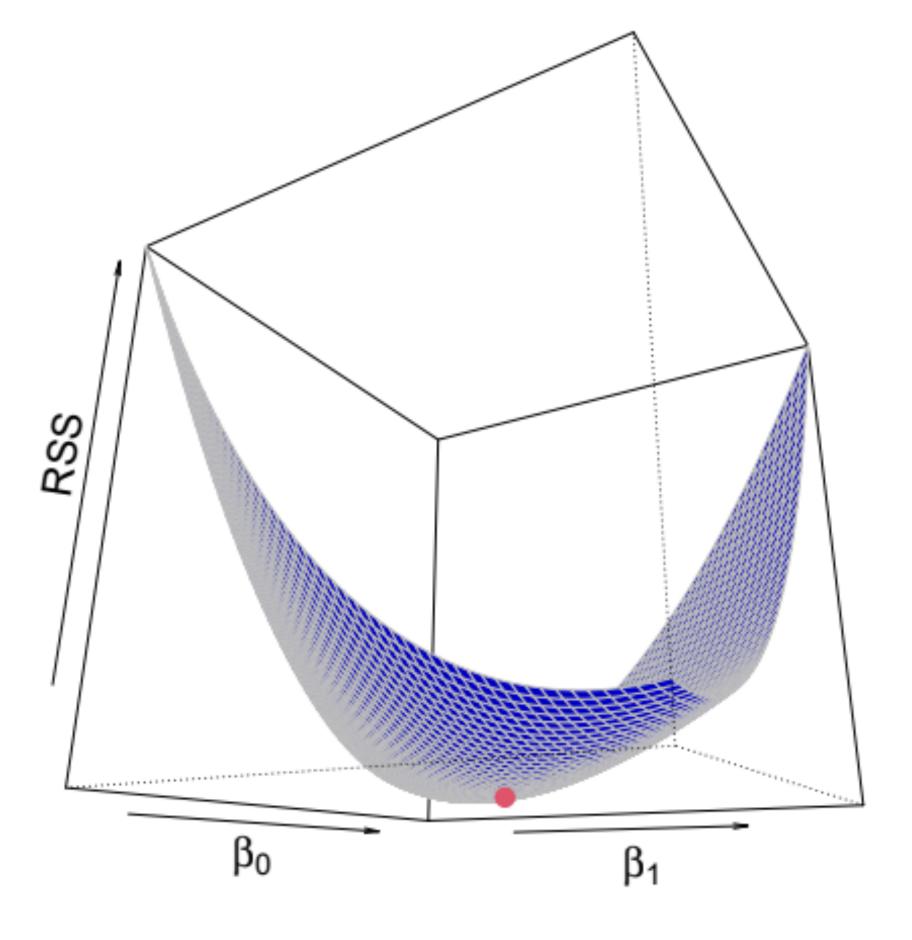
$$w_{0} = \frac{1}{n} \sum_{i=1}^{n} y_{i} - w_{1}x_{i}$$

$$w_{1} = \frac{n \sum_{i} x_{i}y_{i} - \left(\sum_{i} x_{i}\right)\left(\sum_{i} y_{i}\right)}{n \sum_{i} x_{i}^{2} - \left(\sum_{i} x_{i}\right)^{2}}$$

• Solution is unique because the cost function is convex in the parameters





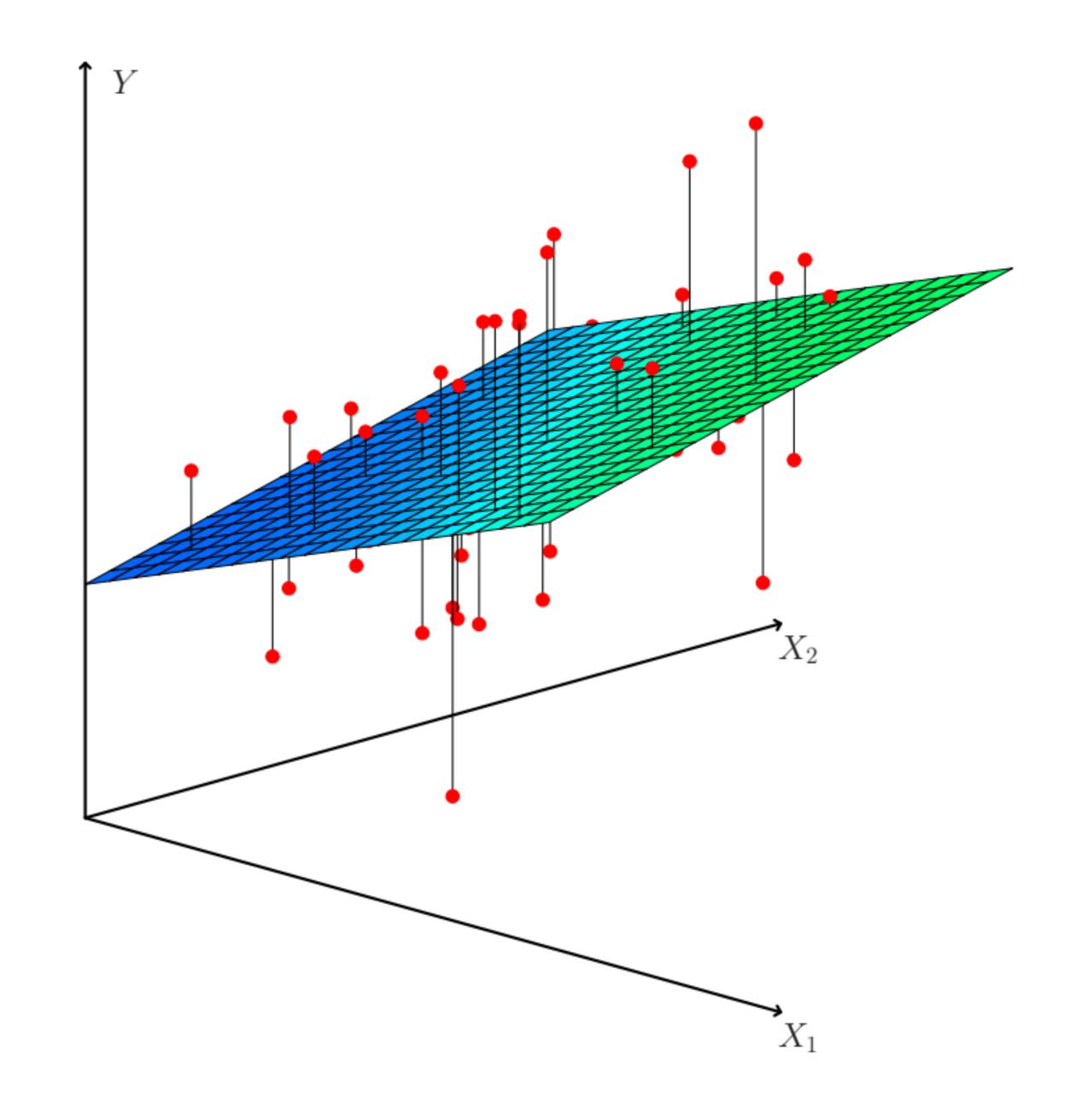


#### Linear regression with multiple features

- Every data point is now a *vector* of features:  $\mathbf{x} = (x_1, x_2, ..., x_p)$
- Notation: use superscripts to index into training set:  $\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(n)}$
- Hypothesis class: linear models from feature tuples  $(x_1, ..., x_p)$  to real numbers:

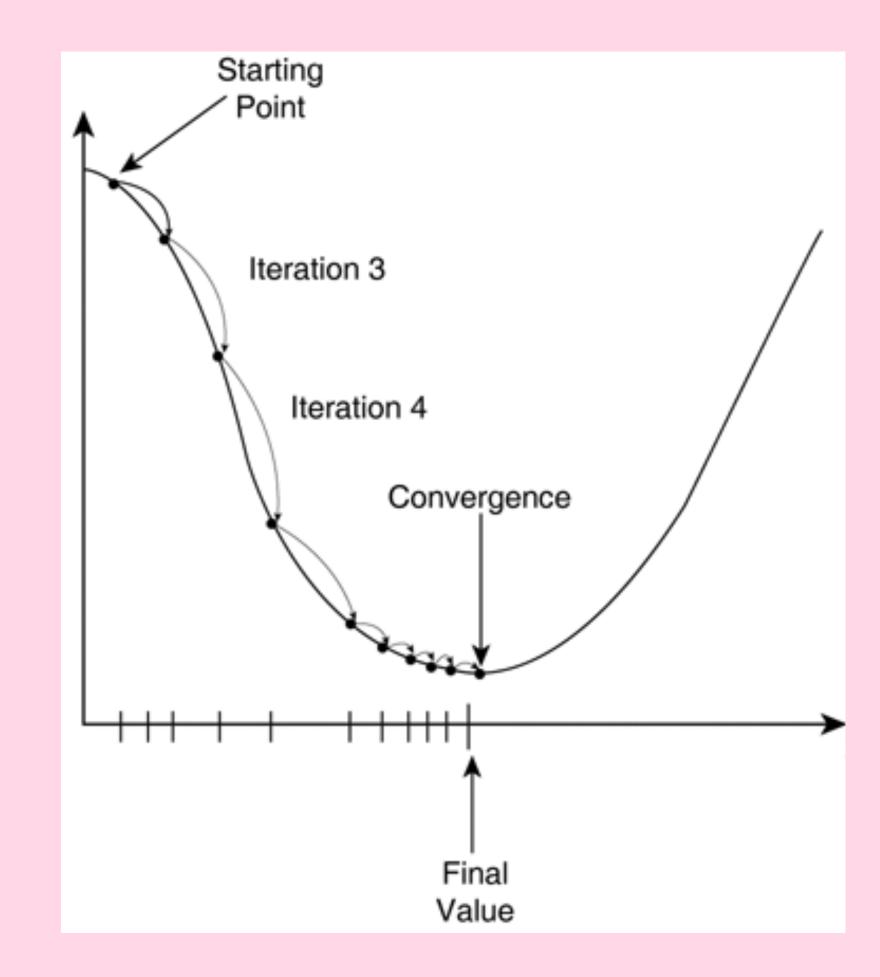
$$h(\mathbf{x}) = \mathbf{w}^{\mathsf{T}} \mathbf{x} + w_0 = w_0 + \sum_{j=1}^{p} w_j x_j$$

- Can use *multivariable* calculus to derive analytical solution:  $\mathbf{w} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$  for data matrix  $\mathbf{X}$  and label vector  $\mathbf{y}$
- Candidate hypotheses are hyperplanes in (p + 1)-dimensional space



## Alternative optimizer: gradient descent

- Goal: pick parameters w to minimize cost function  $C(\mathbf{w})$
- Basic idea: roll downhill
- How do you know which way is downhill?
- In one dimension, use the derivative
  - Positive derivative: step left
  - Negative derivative: step right
  - Step size should be proportional to magnitude of derivative
- Rule:  $w \leftarrow w \eta \frac{d}{dw} C(w)$

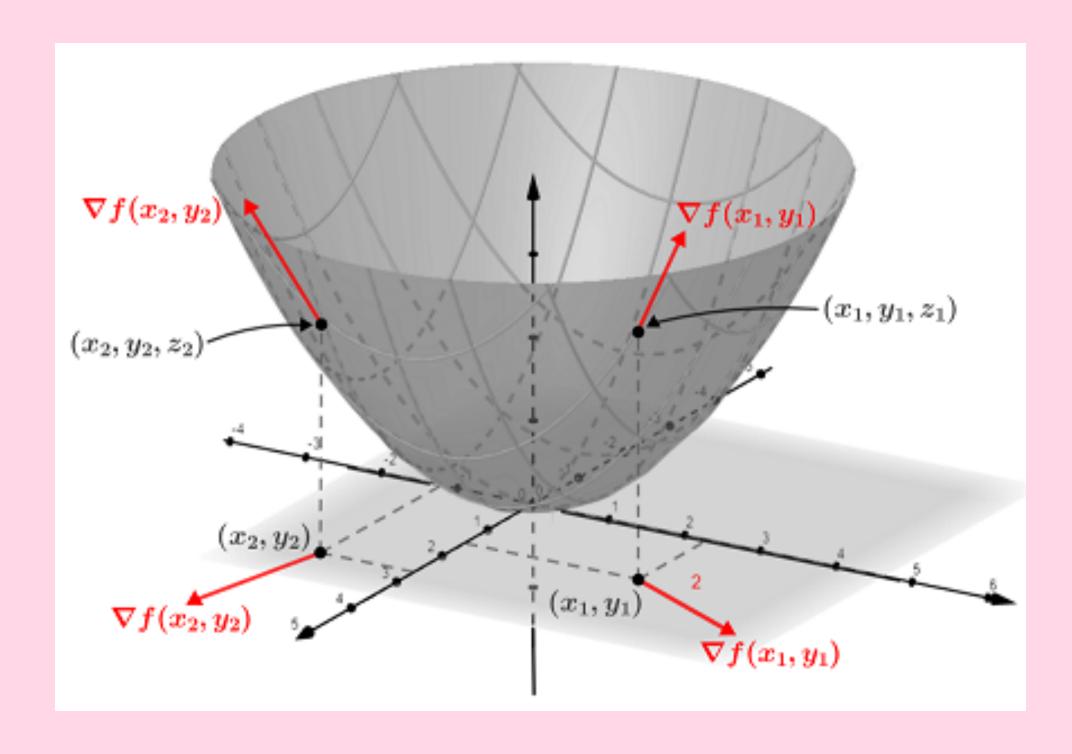


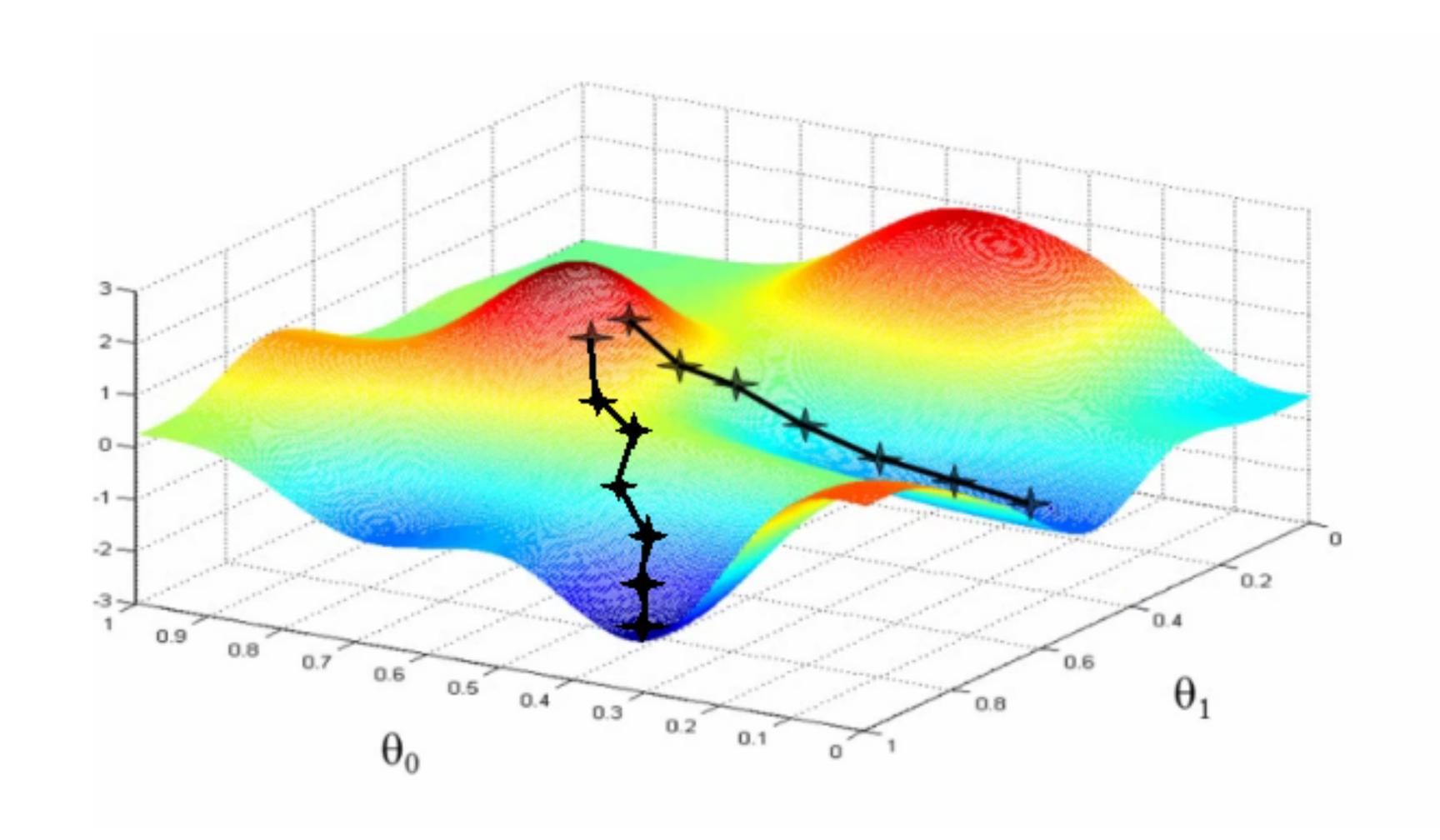
#### Gradient descent in several dimensions

• In several dimensions, use the gradient

$$\nabla_{\mathbf{w}} C(\mathbf{w}) = \left( \frac{\partial}{\partial w_1} C(\mathbf{w}), \dots, \frac{\partial}{\partial w_p} C(\mathbf{w}) \right)$$

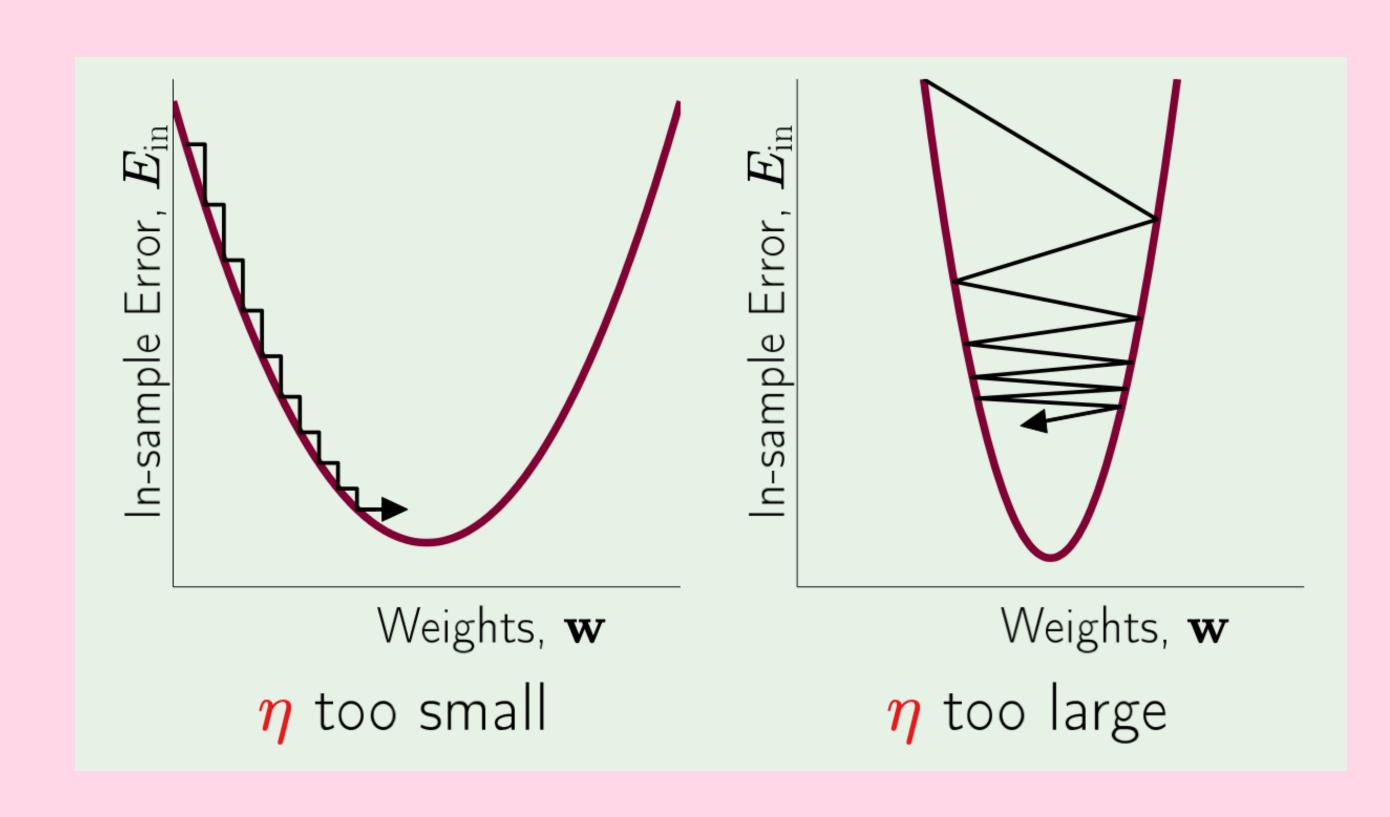
- The gradient is a vector that points in the direction of steepest ascent, with magnitude proportional to the slope in that direction
- For minimization, need to go the opposite direction of the gradient
- Rule:  $\mathbf{w} \leftarrow \mathbf{w} \eta \nabla_{\mathbf{w}} C(\mathbf{w})$





#### Problems with gradient descent

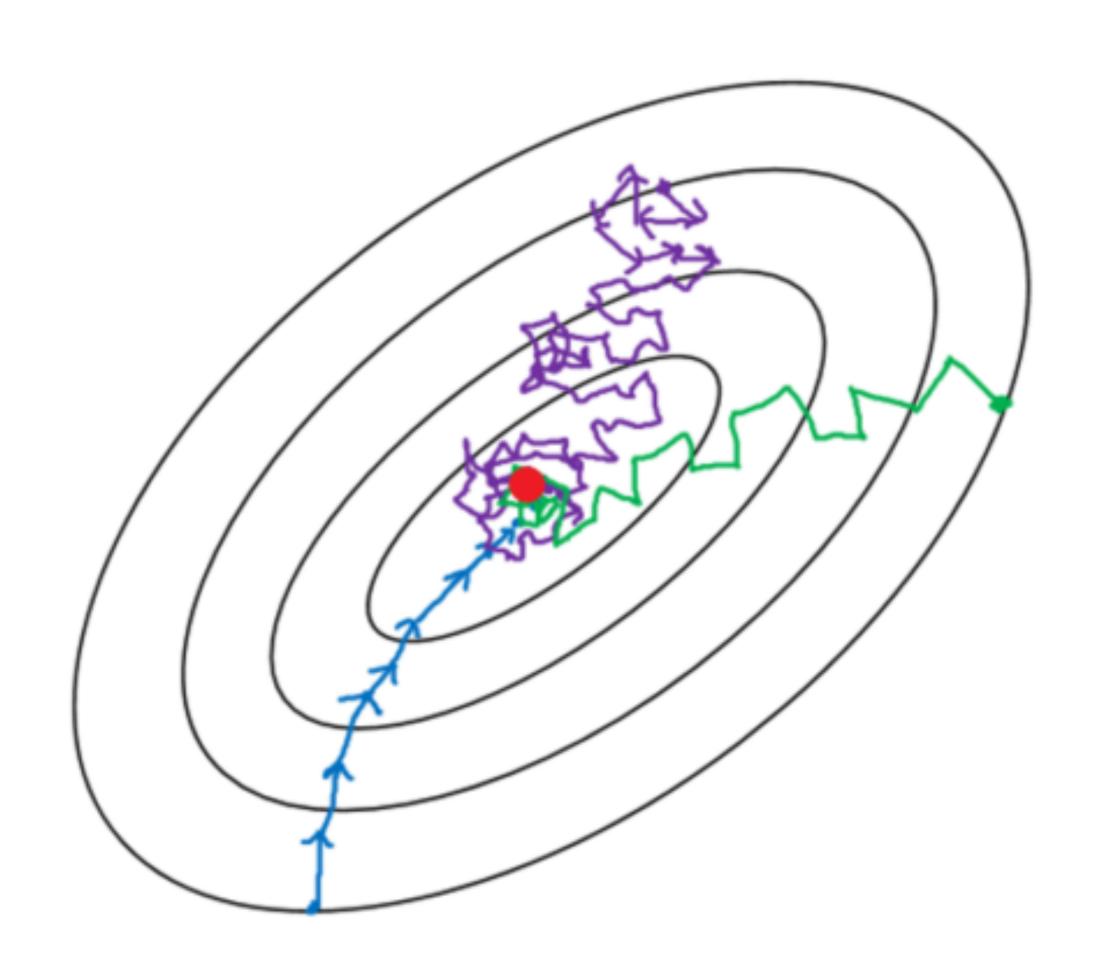
- What can go wrong with rolling downhill?
- Might converge to a *local* minimum instead of a *global* minimum
- Wrong step size η can lead to slow/no convergence
- Evaluating  $\nabla_{\mathbf{w}} C(\mathbf{w})$  requires a pass through the entire training dataset; this is slow if the dataset is large



## Stochastic gradient descent

$$C(\mathbf{w}) = \sum_{i=1}^{n} c\left(h_{\mathbf{w}}(\mathbf{x}^{(i)}), y^{(i)}\right)$$

- Evaluating  $\nabla_{\mathbf{w}} C(\mathbf{w})$  requires a pass through the entire training dataset
- Training dataset might contain n = millions of examples
- Instead of using all *n* examples, take a sample of size *b* (typically  $b \approx 50$ )
- This sample is called a minibatch
- We can estimate  $\nabla_{\mathbf{w}} C(\mathbf{w})$  using just the examples in the minibatch



- Batch gradient descent
- Mini-batch gradient Descent
- Stochastic gradient descent