# Artificial Intelligence csc 665

#### Administrivia

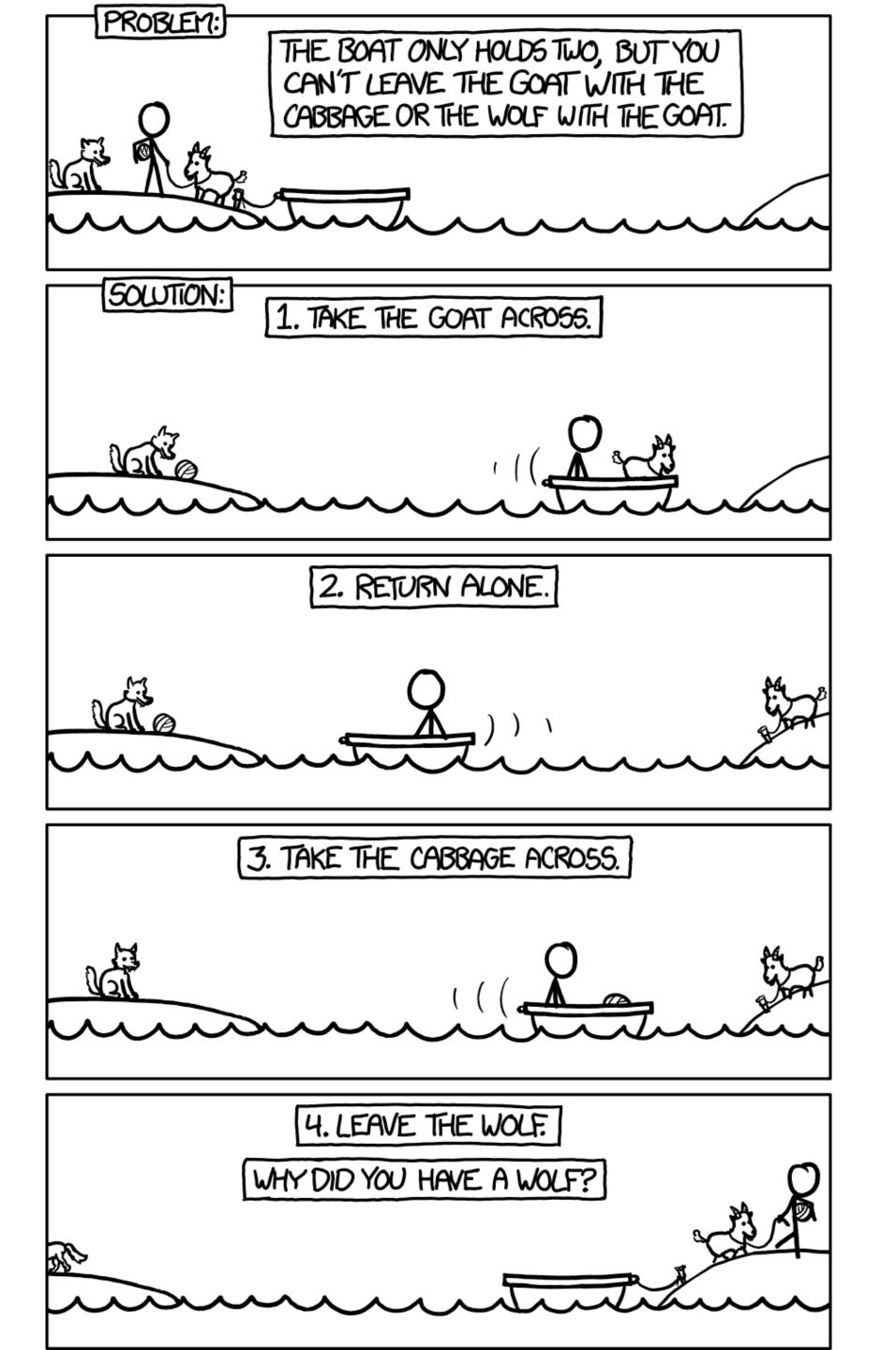
- Who in this room is not enrolled?
- Office hours are in effect: before class on Tuesdays, after class on Thursdays @ Thornton 434
- Homework o due tomorrow at 11:59 pm earn extra credit and calibrate your level of preparation
- All homeworks can be submitted up to 5 days late, with a 10% penalty per day
- You get one late waiver during the semester to apply (retroactively) to any late homework, eliminating the late penalty
- Midterms are in-person and cannot be made up

### Search

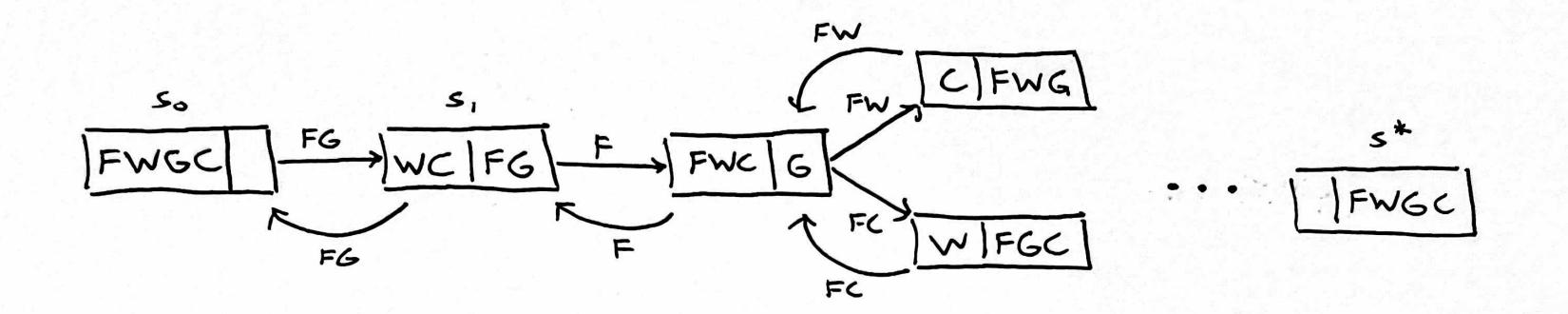
2.6.2024

- Search: make decisions by looking ahead
- Logic: deduce new facts from existing facts
- Constraints: find a way to satisfy a given specification
- Probability: reason quantitatively about uncertainty
- Learning: make future predictions from past observations

## Goat example



#### [search tree for goat problem on board]



$$Actions(s_0) = \{FG\}$$

Is 
$$End(s) = \begin{cases} True & \text{if } s = s^* \\ Folse & \text{otherwise} \end{cases}$$

# Modeling

#### Modeling a search problem

Start state:  $s_0$ 

Possible actions: Actions(s)

Action cost: Cost(s, a)

Transition model: Succ(s, a)

Goal test: IsEnd(s)

#### Modeling a search problem

Start state:  $s_0 \in S$ 

Possible actions:  $Actions(s) \subseteq A$ 

Action cost:  $Cost(s, a) \in \mathbb{R}_{\geq 0}$ 

Transition model:  $Succ(s, a) \in S$ 

Goal test:  $IsEnd(s) \in \{True, False\}$ 

state space S, action set A, non-negative real numbers  $\mathbb{R}_{>0}$ 

#### Search graph

- The functions of the search problem induce a graph
- Nodes are states in S
- There is a **directed edge**  $s \to s'$  if Succ(s, a) = s' for some action  $a \in Actions(s)$
- Edges are labeled with the costs given by Cost(s, a)
- Goal nodes are determined by IsEnd(s)

#### [live coding: modeling search]

### Inference

#### The inference problem

Given: a search graph

Find: a minimum cost path from start to finish in the graph

#### Backtracking search

**Global state:** minimum cost path, set of explored (node, cost) pairs **function** search(*s*, path) :

- if lsEnd(s):
  - update the minimum cost path
- for each action  $a \in Actions(s)$ :
  - if Succ(s, a) hasn't been explored at Cost(s, a) yet:
    - add (Succ(s, a), Cost(s, a)) to the explored set
    - extend path with Succ(s, a) and Cost(s, a)
    - recurse: search(Succ(s, a), path)